

In re Appln. of Joseph F. Wenzl et al.
Application No. 09/924,668

LISTING OF CLAIMS

1. (Currently Amended) A security gate assembly comprising:

an elongate gate arm of sufficient length to impede the passage of a conventional
automotive vehicle driven by a person and movable along a defined pathway of travel;

a DC motor having an output disposed to provide a torque upon receipt of a first
series of output pulses;

a linkage mechanism attached to one end of said gate arm and to the DC motor
output and disposed to cause rotation of the gate arm in accordance with the DC motor
output; and

an adaptive control circuit disposed to monitor a plurality of operating conditions
and to provide said first output pulses to said DC motor in response to the plurality of
operating conditions.
2. (Original) The invention as in claim 1 wherein the adaptive control circuit is
further disposed to provide second output pulses to cause counter-rotation of the gate arm.
3. (Previously Presented) The invention as in claim 1 wherein the adaptive
control circuit is operable to develop a signal indicative of the position of the gate arm
and to vary the first output signals in accordance with said signal indicative of the
position of the gate arm.
4. (Previously Presented) The invention as in claim 3 wherein said signal
indicative of the position of the gate arm is developed by counting output pulses of the
DC gear motor.

In re Appln. of Joseph F. Wenzl et al.
Application No. 09/924,668

5. (Canceled) The invention as in claim 3 wherein the adaptive control circuit is further operable to receive data to provide the first output signals based on the weight of the gate arm.

6. (Previously Presented) The invention as in claim 1 wherein the adaptive control circuit senses a relative position and speed of the gate arm as it traverses its defined pathway of travel.

7. (Previously Presented) The invention as in claim 6 wherein the adaptive control circuit provides an output signal to the DC motor to cause the gate arm to cease movement along the pathway of travel when a change in angular velocity is sensed.

8. (Canceled) The invention as in claim 1 wherein the linkage mechanism comprises a four-bar linkage member for coupling said DC motor output with said gate arm.

9. (Previously Presented) The invention as in claim 17 wherein said linkage mechanism further includes a banana-shaped link piece attached to both said DC motor output and said gate arm.

10. (Original) The invention as in claim 9 wherein the adaptive control circuit comprises a microprocessor and an object-oriented control program executing on said microprocessor.

11. (Previously Presented) The invention as in claim 10 wherein the object-oriented control program creates an instance of a motor controller class that specifies control parameters.

12. (Canceled) An object-oriented control system implementing a control program in a security gate including a gate arm and a motor operably connected thereto

In re Appln. of Joseph F. Wenzl et al.
Application No. 09/924,668

and adapted to be actuated and deactuated upon the receipt of a series of control pulses comprising:

- a motor controller object implementing methods and data associated with a security gate;

- a device handler object implementing methods data associated with input and output functions; and

- a messaging object for permitting messages to be passed between the motor controller object and the device handler object.

13. (Canceled) The invention as in claim 12 wherein the motor controller object accesses one of a plurality of output voltage profiles for actuating the gate arm.

14. (Canceled) A linkage assembly for coupling a gate arm with an actuating motor comprising:

- a reduction gear mechanism coupled with the actuating motor output;

- a first link piece connected with the reduction gear mechanism;

- a crank shaft operably connected with the gate arm having an axis of rotation spaced from the output axis of rotation; and

- a second link piece operably connecting the first link piece with the crank shaft.

15. (Canceled) The invention as in claim 15 wherein the main crank passes through a centerline of the gate arm to permit connection in either a right-hand orientation or a left-hand orientation.

16. (Currently Amended) A security gate assembly comprising:

- an elongate gate arm movable along a defined pathway of travel;

In re Appln. of Joseph F. Wenzl et al.
Application No. 09/924,668

a DC motor having an output disposed to provide a torque upon receipt of a first series of output pulses;

a linkage mechanism attached to one end of said gate arm and to the DC motor output and disposed to cause rotation of the gate arm in accordance with the DC motor output; and

an adaptive control circuit disposed to monitor a plurality of operating conditions including data concerning the weight of the gate arm, and to develop a signal indicative of the position of the gate arm, said adaptive control circuit providing said first output pulses to said DC motor in response to the plurality of operating conditions including the weight of the gate arm such that said first output pulses are ~~varied~~ varied in accordance with at least said signal indicative of the position of the gate arm and said data concerning the weight of the gate arm.

17. (Previously Presented) A security gate assembly comprising:

an elongate gate arm movable along a defined pathway of travel;

a DC motor having an output disposed to provide a torque upon receipt of a first series of output pulses;

a linkage mechanism including a four-bar linkage member disposed to couple one end of said gate arm with the DC motor output and disposed to cause rotation of the gate arm in accordance with the DC motor output; and

an adaptive control circuit disposed to monitor a plurality of operating conditions and to provide said first output pulses to said DC motor in response to the plurality of operating conditions.

In re Appln. of Joseph F. Wenzl et al.
Application No. 09/924,668

18. (Previously Presented) The invention as in claim 16 wherein said elongate gate arm is of sufficient length to impede the passage of a motor vehicle.

19. (Previously Presented) The invention as in claim 17 wherein said elongate gate arm is of sufficient length to impede the passage of a motor vehicle.

20. (New) The invention as in claim 16 wherein the adaptive control circuit is further disposed to provide second output pulses to cause counter-rotation of the gate arm.

21. (New) The invention as in claim 16 wherein the adaptive control circuit senses a relative position and speed of the gate arm as it traverses its defined pathway of travel.

22. (New) The invention as in claim 21 wherein the adaptive control circuit provides an output signal to the DC motor to cause the gate arm to cease movement along the pathway of travel when a change in angular velocity is sensed.